

Goal: Discretize 2nd order linear differential eqn

i.e. convert differential eqn
 $y'' + p(t)y' + q(t)y = f(t)$

to matrix eqn

$$D y = \underline{f}$$

D = matrix of numbers

y = vector of unknowns.

\underline{f} = vector of numbers

First we will discretize using pointwise formulas

$$\rightarrow y'_k = \text{centered difference} \\ = \frac{1}{2h} (y_{k+1} - y_{k-1})$$

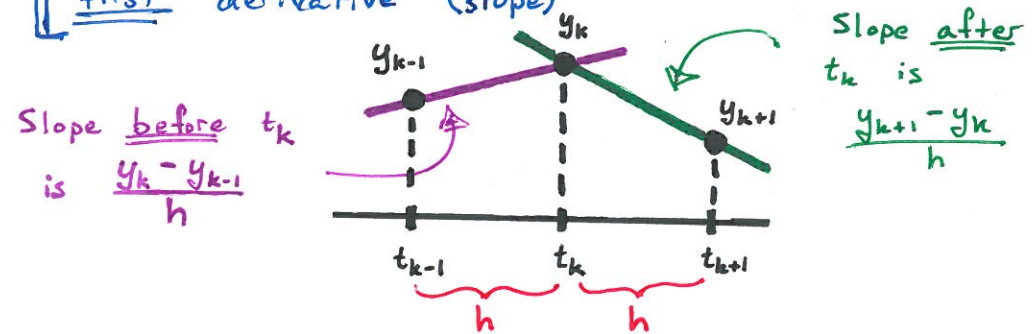
$$\rightarrow y''_k = ??$$

Pointwise 2nd Derivative Formula.

$$y''_k = \frac{1}{h^2} (y_{k+1} - 2y_k + y_{k-1})$$

$\frac{d^2}{dt^2}$ Formula.

Second derivative is change in
first derivative (slope)

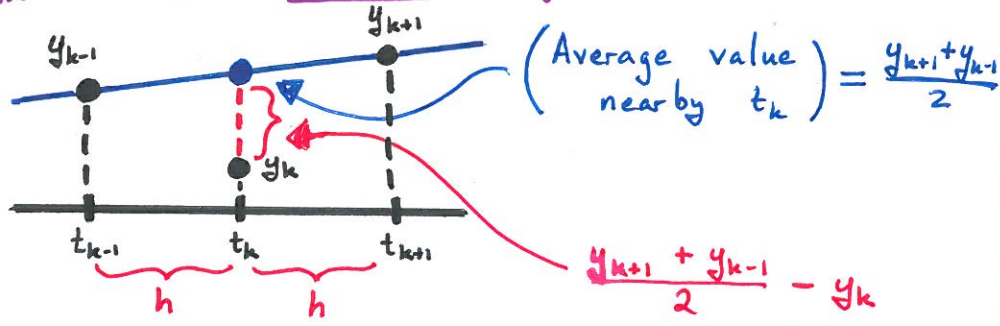


$$\begin{aligned} \frac{\text{Change in slope at } t_k}{h} &= \frac{\left(\frac{y_{k+1} - y_k}{h}\right) - \left(\frac{y_k - y_{k-1}}{h}\right)}{h} \\ &= \frac{y_{k+1} - 2y_k + y_{k-1}}{h^2} \end{aligned}$$

Note: This formula is a backward diff. of forward differences

$$y''_k = \frac{\frac{y_{k+1} - y_k}{h} - \frac{y_k - y_{k-1}}{h}}{h} = \frac{y'_k - y'_{k-1}}{h}$$

Remark: An alternate way to understand $\frac{d^2}{dt^2}$ is to note that it measures difference between y_k and average value nearby



$$\begin{aligned}
 y_k'' &= \frac{1}{h^2/2} \left(\frac{y_{k+1} + y_{k-1}}{2} - y_k \right) \\
 &= \frac{2}{h^2} \left(\frac{y_{k+1} + y_{k-1} - 2y_k}{2} \right) \\
 &= \frac{1}{h^2} (y_{k+1} - 2y_k + y_{k-1})
 \end{aligned}$$

EX: Compute $\frac{d^2}{dt^2}$ of $\underline{f} = \begin{bmatrix} 1 \\ 0 \\ -1 \\ -2 \\ 1 \end{bmatrix}$ with $h = \frac{1}{2}$.

$$\begin{aligned}
 f_0 &= 1 \rightarrow f_0'' = \frac{1}{h^2}(f_1 - 2f_0 + f_{-1}) \text{ cannot be computed} \\
 f_1 &= 0 \rightarrow f_1'' = \frac{1}{h^2}(f_2 - 2f_1 + f_0) = 4(-1 - 0 + 1) = 0 \\
 f_2 &= -1 \rightarrow f_2'' = \frac{1}{h^2}(f_3 - 2f_2 + f_1) = 4(-2 + 2 + 0) = 0 \\
 f_3 &= -2 \rightarrow f_3'' = \frac{1}{h^2}(f_4 - 2f_3 + f_2) = 4(1 + 4 - 1) = 16 \\
 f_4 &= 1 \rightarrow f_4'' = \frac{1}{h^2}(f_5 - 2f_4 + f_3) \text{ cannot be computed}
 \end{aligned}$$

In matrix form

$$\begin{bmatrix} f_1'' \\ f_2'' \\ f_3'' \\ \vdots \\ f_n'' \end{bmatrix} = \frac{1}{h^2} \begin{bmatrix} 1 & -2 & 1 & 0 & \dots & 0 \\ 0 & 1 & -2 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & 1 & -2 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \\ \vdots \\ f_n \\ f_{n+1} \end{bmatrix}$$

2^{nd} Derivative Matrix.

EX Compute f'' for $f = \begin{bmatrix} 1 \\ 2 \\ 0 \\ -1 \\ 2 \end{bmatrix}$ with $h = \frac{1}{3}$.

$$\begin{aligned}
 \begin{bmatrix} f_1'' \\ f_2'' \\ f_3'' \end{bmatrix} &= \frac{1}{(\frac{1}{3})^2} \begin{bmatrix} 1 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 0 \\ -1 \\ 2 \end{bmatrix} \\
 &= 9 \begin{bmatrix} 1 - 4 + 0 \\ 2 - 0 - 1 \\ 0 + 2 + 2 \end{bmatrix} = 9 \begin{bmatrix} -3 \\ 1 \\ 4 \end{bmatrix}
 \end{aligned}$$

We can use the pointwise second derivative formula to discretize 2nd order differential eqns.

$$y_k'' = \frac{1}{h^2} (y_{k+1} - 2y_k + y_{k-1})$$

EX: Discretize

$$-y'' = 4t - 1 \text{ with } \underline{y(1)} = 0, \underline{y(3)} = 0 \text{ on } [1, 3] \text{ with } h = \frac{1}{2}.$$

Note: Since this is a 2nd order DE (with y'') solving requires two integrations, yielding two unknown constants. Problem must include two values.

- at same point $\begin{cases} y(a) = \dots \\ y'(a) = \dots \end{cases}$
"initial value" problem (IVP)

- at different points $\begin{cases} y(a) = \dots \\ y(b) = \dots \end{cases}$
"boundary value" problem (BVP)

Boundary value problems are more difficult to solve, so we will focus on discretizing them.

t y

$t_0 = 1$ $y_0 = y(t_0) = y(1) = 0$ \leftarrow Boundary value determines first y ($y_0 = 0$)

$t_1 = \frac{3}{2}$

$t_2 = 2$

$t_3 = \frac{5}{2}$

$t_4 = 3$ $y_4 = y(t_4) = y(3) = 0$ \leftarrow Boundary value determines last y ($y_{n+1} = 0$)

unknown $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$ $\xrightarrow{\text{plus into DE}}$ $\begin{cases} -y_1'' = 4t_1 - 1 \\ -y_2'' = 4t_2 - 1 \\ -y_3'' = 4t_3 - 1 \end{cases}$

$$\begin{cases} -\frac{1}{h^2} (y_2 - 2y_1 + y_0) = -y_1'' = 4t_1 - 1 = 4 \cdot \frac{3}{2} - 1 = 5 \\ -\frac{1}{h^2} (y_3 - 2y_2 + y_1) = -y_2'' = 4t_2 - 1 = 4 \cdot 2 - 1 = 7 \\ -\frac{1}{h^2} (y_4 - 2y_3 + y_2) = -y_3'' = 4t_3 - 1 = 4 \cdot \frac{5}{2} - 1 = 9 \end{cases}$$

$\frac{1}{h^2} = \frac{1}{(\frac{1}{2})^2} = \frac{1}{\frac{1}{4}} = 4$

$$\begin{cases} -4y_2 + 8y_1 = 5 \\ -4y_3 + 8y_2 - 4y_1 = 7 \\ 8y_3 - 4y_4 = 9 \end{cases} \Rightarrow \begin{bmatrix} 8 & -4 & 0 \\ -4 & 8 & -4 \\ 0 & -4 & 8 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \\ 9 \end{bmatrix}$$

(alt. $\frac{1}{(\frac{1}{2})^2} \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \\ 9 \end{bmatrix}$)

Since we know y_0 & y_{n+1} from boundary values, we can use centered differences for y' in boundary value problems.

EX: Discretize

$y'' + 2y' = t + 1$ with $y(2) = 0$ $y(3) = 0$
 using step-size $h = 1/5$

Note: The interval should always be between the two boundary points - in this case $[2, 3]$.

t	y	$y'' + 2y' = t + 1$
$t_0 = 2$	$y_0 = 0$	
$t_1 = 11/5$	unknown $\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix}$	$\begin{cases} \frac{1}{h^2}(y_2 - 2y_1 + y_0) + 2 \frac{1}{2h}(y_2 - y_0) = \frac{11}{5} + 1 \\ \frac{1}{h^2}(y_3 - 2y_2 + y_1) + 2 \frac{1}{2h}(y_3 - y_1) = \frac{12}{5} + 1 \\ \frac{1}{h^2}(y_4 - 2y_3 + y_2) + 2 \frac{1}{2h}(y_4 - y_2) = \frac{13}{5} + 1 \\ \frac{1}{h^2}(y_5 - 2y_4 + y_3) + 2 \frac{1}{2h}(y_5 - y_3) = \frac{14}{5} + 1 \end{cases}$
$t_2 = 12/5$		
$t_3 = 13/5$		
$t_4 = 14/5$		
$t_5 = 3$	$y_5 = 0$	

(Combine terms)

$\frac{1}{h^2} = \frac{1}{(1/5)^2} = \frac{1}{1/25} = 25$ $\frac{1}{h} = \frac{1}{1/5} = 5$

$$\begin{cases} (25+5)y_2 + (-50)y_1 = 16/5 \\ (25+5)y_3 + (-50)y_2 + (25-5)y_1 = 17/5 \\ (25+5)y_4 + (-50)y_3 + (25-5)y_2 = 18/5 \\ (-50)y_4 + (25-5)y_3 = 19/5 \end{cases}$$

$$\begin{bmatrix} -50 & 30 & 0 & 0 \\ 20 & -50 & 30 & 0 \\ 0 & 20 & -50 & 30 \\ 0 & 0 & 20 & -50 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} 16/5 \\ 17/5 \\ 18/5 \\ 19/5 \end{bmatrix}$$

alt: $\left(\frac{1}{(1/5)^2} \begin{bmatrix} -2 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & -2 \end{bmatrix} + 2 \frac{1}{2(1/5)} \begin{bmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{bmatrix} \right) \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 16 \\ 17 \\ 18 \\ 19 \end{bmatrix}$

$\underbrace{\hspace{10em}}_{d^2/dt^2} + 2 \underbrace{\hspace{10em}}_{d/dt}$

For 2nd order differential equations, the (fixed-fixed) second derivative matrix is

Ex: $\frac{1}{h^2} \begin{bmatrix} \times & -2 & 1 & 0 & 0 & \dots & 0 \\ & 1 & -2 & 1 & 0 & & \\ & 0 & 1 & -2 & 1 & & \\ & \vdots & & & & & \\ & 0 & \dots & 0 & 1 & -2 & \times \end{bmatrix}$

$\begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix}$

$\begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix}$

$\begin{bmatrix} -2 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 1 & -2 \end{bmatrix}$

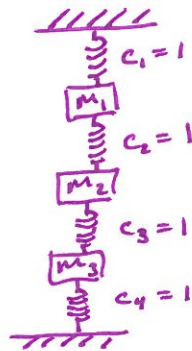
For 2nd order differential equations, the (fixed-fixed) first derivative matrix is

$$\frac{1}{2h} \begin{bmatrix} 0 & 1 & 0 & 0 & \dots & 0 \\ -1 & 0 & 1 & 0 & \dots & 0 \\ 0 & -1 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & -1 & 0 & \dots \end{bmatrix} \quad \left(\begin{array}{l} \text{EX: } \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \\ \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \end{array} \right)$$

Note: The (fixed-fixed) negative 2nd derivative $(-\frac{d^2}{dt^2})$ matrix is the stiffness matrix for a spring system!

$$K = - \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \quad \text{stiffness matrix of}$$



(line of masses with fixed ends)

EX: Discretize $y'' + ty = \delta(t)$ $y(-1) = 0$ $y(1) = 0$ with step-size $h = 1/2$. (5)

$$\begin{array}{l} \underline{t} \\ t_0 = -1 \\ t_1 = -1/2 \\ t_2 = 0 \\ t_3 = 1/2 \\ t_4 = 1 \end{array} \quad \begin{array}{l} \underline{y} \\ y_0 = 0 \\ \text{unknown } \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \\ y_4 = 0 \end{array}$$

$$\underline{y'' + ty = \delta(t-t_0)}$$

$$\left\{ \begin{array}{l} \frac{1}{h^2}(y_2 - 2y_1 + y_0) + (-1/2)y_1 = 0 \\ \frac{1}{h^2}(y_3 - 2y_2 + y_1) + (0)y_2 = 1/h \\ \frac{1}{h^2}(y_4 - 2y_3 + y_2) + (1/2)y_3 = 0 \end{array} \right\}$$

Impulse Point

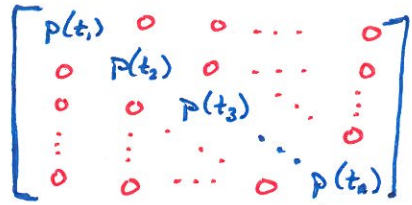
Note: $1/h^2 = 1/(1/2)^2 = 1/(1/4) = 4$
 $1/h = 1/(1/2) = 2$

$$\left\{ \begin{array}{l} 4y_2 + (-8 - 1/2)y_1 = 0 \\ 4y_3 + (-8 + 0)y_2 + 4y_1 = 2 \\ (-8 + 1/2)y_3 + 4y_2 = 0 \end{array} \right\} \Rightarrow \begin{bmatrix} -8.5 & 4 & 0 \\ 4 & -8 & 4 \\ 0 & 4 & -7.5 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$$

$$\underline{alt}: \left(\frac{1}{(1/2)^2} \begin{bmatrix} -2 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -2 \end{bmatrix} + \begin{bmatrix} -1/2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1/2 \end{bmatrix} \right) \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$$

$\frac{d^2}{dt^2} + t$

For 2nd order differential equations, the "multiply by $p(t)$ " matrix is



Types of Boundary Values.

- A boundary value problem with conditions

$$\begin{cases} y(a) = \text{something} \\ y(b) = \text{something} \end{cases}$$

is called "fixed-fixed" because the boundary conditions hold the endpoints of y still ("fixing" them in place) no matter what the forcing function $f(t)$ is.

- A boundary value problem with conditions

$$\begin{cases} y(a) = \text{something} \\ y'(b) = \text{something} \end{cases}$$

is called "fixed-free" because different forcing functions could change the right endpoint $y(b)$

$$\begin{cases} y(a) = 0 \\ y(b) = 0 \end{cases} \text{ "fixed fixed"}$$

$$\begin{cases} y(a) = 0 \\ y'(b) = 0 \end{cases} \text{ "fixed free"}$$

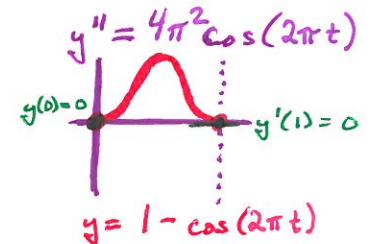
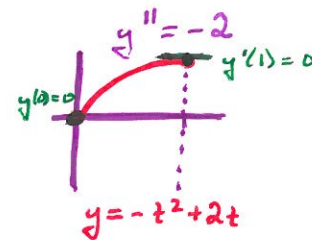
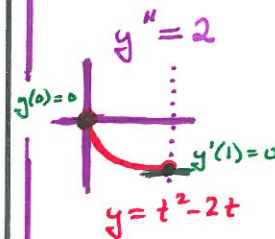
$$\begin{cases} y'(a) = 0 \\ y(b) = 0 \end{cases} \text{ "free fixed"}$$

$$\begin{cases} y'(a) = 0 \\ y'(b) = 0 \end{cases} \text{ "free free"}$$

The same notation is used when discussing variations of the heat and wave equation in MAT 219 ("free" \leftrightarrow "insulated end")

Solutions to "fixed-free" BVP

$$y'' = f(t) \quad y(0) = 0 \quad y'(1) = 0$$



- $y(0)$ is "fixed" at 0
- but $y(1)$ is "free" to move

